

# A Theory of Experimenters

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- ▶ However, standard models of information acquisition fail to explain key feature of experimental practice: randomization
  - RCTs are mixed strategies over experimental assignments  
→ never strictly optimal for Bayesian decision maker

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  - provides insight into open problems for experimental practice

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It does reduce robustness, but very slowly

## An example: a voucher experiment

- ▶ A school district superintendent wants to do an experiment
- ▶ Her prior puts a lot of weight on the idea that private schools are all about selection and that private school students will do equally well in private and public schools
- ▶ However she allows that there is some probability that private schools are better and that all children would do much better there
- ▶ She has one slot in a private school: how should she allocate it?
- ▶ Clearly giving it to a poor child maximizes her learning.

# The experiment continues

- ▶ Now suppose the superintendent assigns one more child to the experiment.
- ▶ The best design under her priors will be to assign a rich child to the public school and a poor child to a private school.
- ▶ No randomization
- ▶ Not balanced. A Bayesian may not want balance.
  - Contrast with Kasy (2014)
- ▶ Even if she only had two children who were both poor for the experiment, she has no reason to randomize.

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- ▶ E.g., vaccinate school children or not, reorganize production lines

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- ▶ Generates outcome data  $y = (y_i)_{i \in \{1, \dots, N\}} \in \mathcal{Y}$
- ▶ Allocation rule  $\alpha : E \times \mathcal{Y} \rightarrow \Delta(\{0, 1\})$

# Natural Model

## Subjective expected utility maximizer (Bayesian)

- ▶ Picks  $\mathcal{E}, \alpha$  solving

$$\max_{\mathcal{E}, \alpha} \mathbb{E}_h[u(\alpha, p)]$$

for prior  $h \in \Delta(\mathcal{P})$  over state of the world  $p$

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Payoff from experiment  $\mathcal{E}$ :

$$\mathbb{E}_{e,y \sim \mathcal{E}} \max_{a \in \{0,1\}} \mathbb{E}_h[u(p, a) | e, y]$$

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*prior gives you a comparison point even with a single outcome*
- ▶ With a prior, even with two meetings, you might give the same speech at both

# Ambiguity Averse Experimentation

- ▶ Decision maker picks  $\mathcal{E}, \alpha$  solving

$$\max_{\mathcal{E}, \alpha} \lambda \mathbb{E}_{h_0}[u(\alpha, p)] + (1 - \lambda) \min_{h \in H} \mathbb{E}_h[u(\alpha, p)]$$

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## Assumption 1 (Limited Extrapolation).

*For all realized experiments  $e$ , there exists an adversarial prior  $\mathbf{h}$  such that optimal decisions conditional on data are bounded away from first best  
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Can be dispensed with if DM exhibits regret aversion

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*then optimal experiment deterministic and Bayesian optimal for  $h_0$*

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(i) *Optimal experiment (e.g., std RCT) guarantees*

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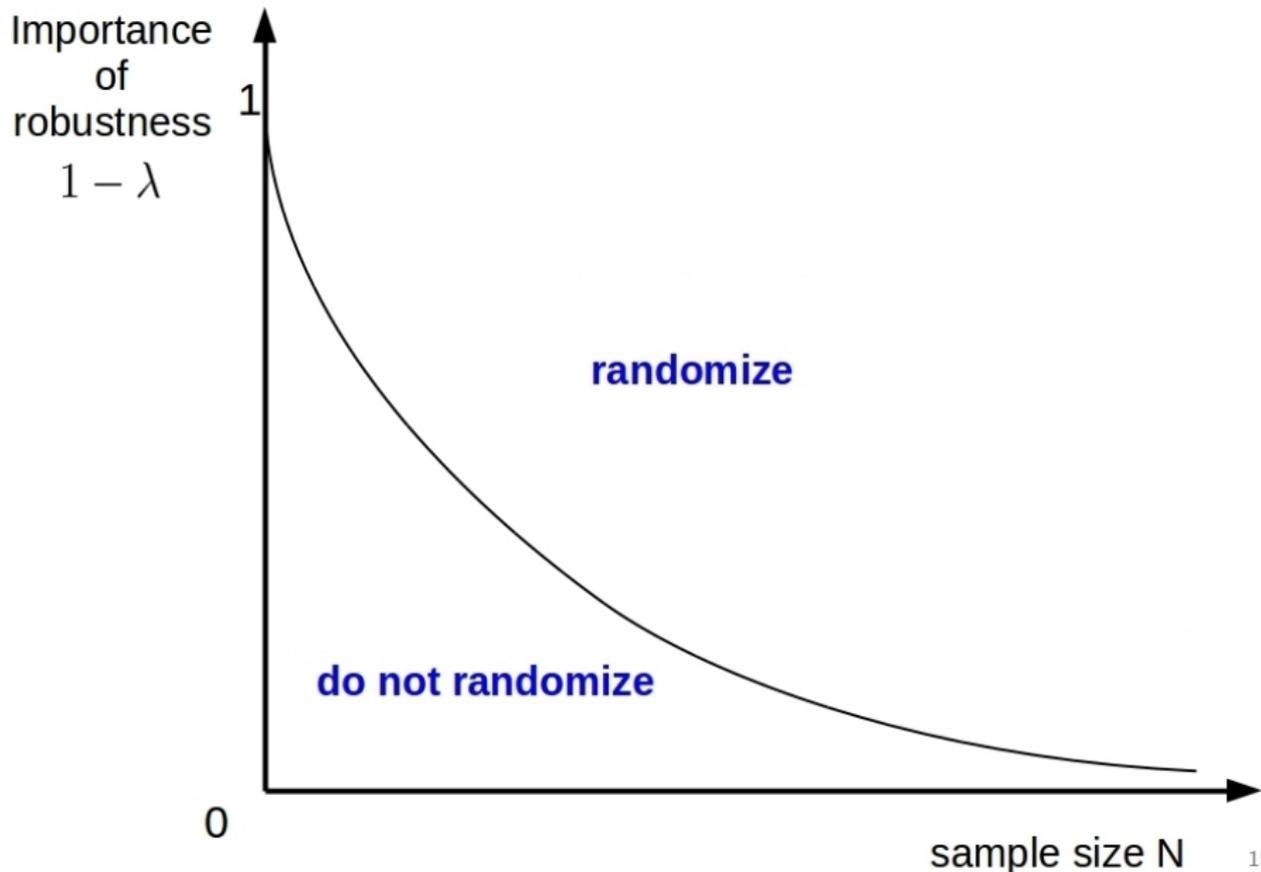
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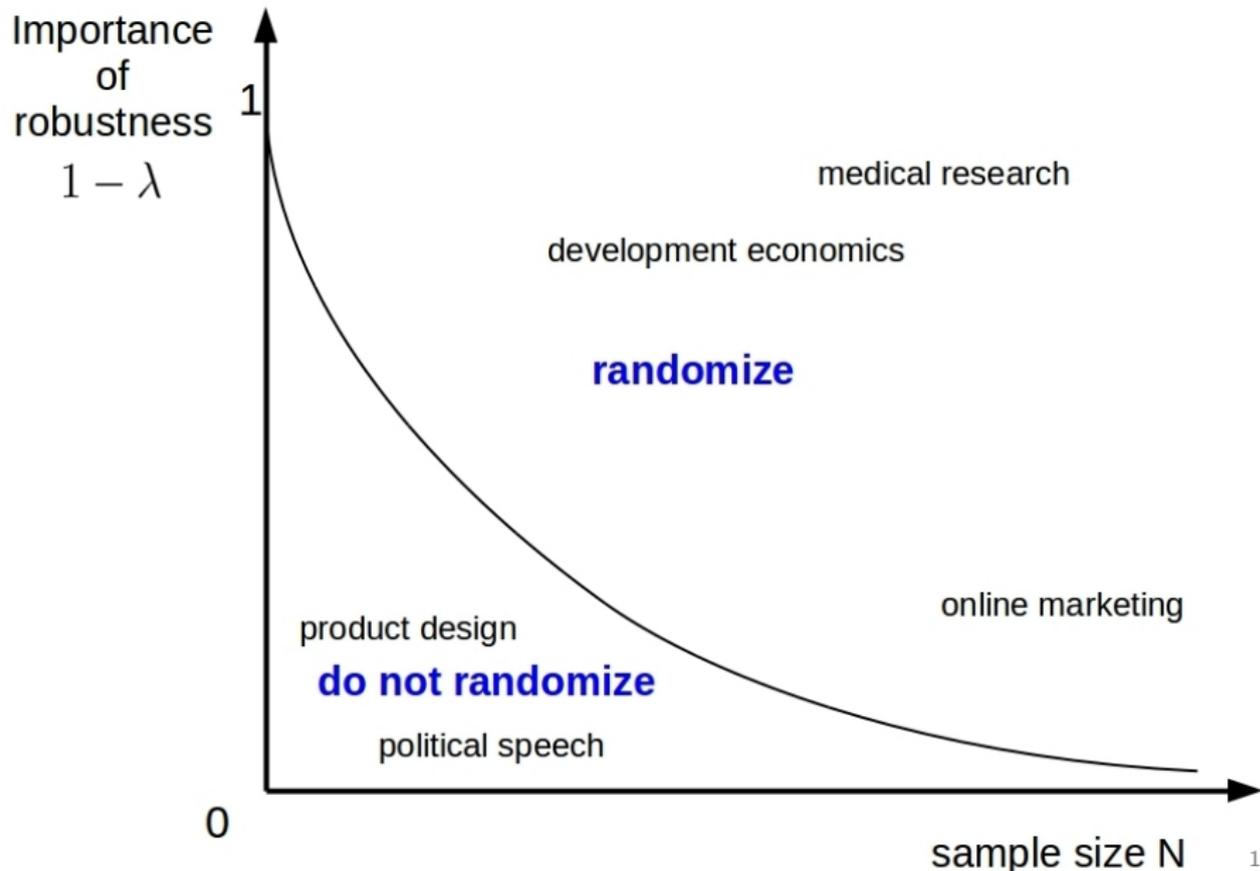
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As sample size  $N$  gets large, **optimal experiment is random**

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  - Randomizing by time of day; see Green and Tuscisny, 2012, for a critique
  - Miguel and Kremer, 2004; see Deaton, 2010 for a critique
- ▶ Implication: RCTs offer near optimal alternative to complexity of solving decision maker's problem exactly, which requires reliably eliciting beliefs (priors)

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- ▶ However, these algorithms create predictable assignments
  - Is this a weakness?
  - Surprisingly, yes: “You picked the wrong variables to block on”

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- ▶ Is this a problem for robustness? Can we quantify it?

# Re-Randomization

Model can be written as

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**$K$  re-randomization:**

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3. Run experiment  $e_K^*$
4. Choose policy according to  $\alpha^* = \arg \max_{a \in \{0,1\}} \bar{y}^a - \bar{y}^{1-a}$

# The Tradeoff of Re-Randomization

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## Proposition 4 (negative impact on robustness).

*There exists  $\rho > 0$  such that, for all  $N$ , if  $K \geq 2^N$ , then*

$$\max_{\alpha} \min_{h \in H} \mathbb{E}_{h, \mathcal{E}_K} [u(p, \alpha(e, y))] < \min_{h \in H} \mathbb{E}_h \left( \max_{a \in \{0,1\}} u(p, a) \right) - \rho.$$

## How Large Are the Costs?

### **Proposition 5 (cost of rerandomization small).**

*A  $K$ -rerandomized experiment  $\mathcal{E}_K$  guarantees*

$$\min_{h \in H} \mathbb{E}_{h, \mathcal{E}_K} [u(p, \alpha(e, y))] \geq \min_{h \in H} \mathbb{E}_h \left( \max_{a \in \{0,1\}} u(p, a) \right) - \sqrt{\frac{\ln(K)}{N/2}}$$

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## Remark 1.

*Bound remains valid regardless of objective function  $B(e)$ , can even choose objective ex post*

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	K	10	50	100	250	500	1000
$\sqrt{\log(K)}$		1.52	1.97	2.15	2.35	2.49	2.63
odds top 5% bal.		0.4	0.92	0.99	1.0	1.0	1.0
odds top 1% bal.		0.1	0.39	0.63	0.92	0.99	1.0

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- ▶ Morgan and Rubin (2012) show that re-randomization increases precision of estimated treatment effect in linear Gaussian model

# What About Standard Errors?

- ▶ Hypothesis testing (using t- or z-stats) is not Bayesian, not due to risk aversion
- ▶ Tetenov (2012) shows that reference dependence (loss aversion or status quo bias) can rationalize hypothesis testing

## **Proposition 6.**

*All of our results extend to using reference dependent preferences*

- ▶ Morgan and Rubin (2012) show that re-randomization increases precision of estimated treatment effect in linear Gaussian model
- ▶ Bungi, Canay, and Shaikh (2016) show this more generally for balanced assignment rules (i.e., symmetric stratification)

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- ▶ If probability that a random assignment is balanced is very small, then procedure above is akin to setting  $K$  very high

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With small samples, we need to be Bayesian — learning necessarily subjective
- ▶ Re-randomization does involve a tradeoff, but cost is small
- ▶ Other questions: subgroup analysis, pre-analysis plans, . . .