

A Theory of Experimenters

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- ▶ Theory should help resolve these debates
- ▶ However, standard models of information acquisition fail to explain key feature of experimental practice: randomization
 - RCTs are mixed strategies over experimental assignments
→ never strictly optimal for Bayesian decision maker

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 - correctly captures the preferences revealed by real-life experimentation
 - provides insight into open problems for experimental practice

Outline of the Talk

- ▶ *Building plausible model of experimentation*

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It does reduce robustness, but very slowly

An example: a voucher experiment

- ▶ A school district superintendent wants to do an experiment
- ▶ Her prior puts a lot of weight on the idea that private schools are all about selection and that private school students will do equally well in private and public schools
- ▶ However she allows that there is some probability that private schools are better and that all children would do much better there
- ▶ She has one slot in a private school: how should she allocate it?
- ▶ Clearly giving it to a poor child maximizes her learning.

The experiment continues

- ▶ Now suppose the superintendent assigns one more child to the experiment.
- ▶ The best design under her priors will be to assign a rich child to the public school and a poor child to a private school.
- ▶ No randomization
- ▶ Not balanced. A Bayesian may not want balance.
 - Contrast with Kasy (2014)
- ▶ Even if she only had two children who were both poor for the experiment, she has no reason to randomize.

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- ▶ Decision maker's payoff

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- ▶ E.g., vaccinate school children or not, reorganize production lines

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- ▶ Generates outcome data $y = (y_i)_{i \in \{1, \dots, N\}} \in \mathcal{Y}$
- ▶ Allocation rule $\alpha : E \times \mathcal{Y} \rightarrow \Delta(\{0, 1\})$

Natural Model

Subjective expected utility maximizer (Bayesian)

- ▶ Picks \mathcal{E}, α solving

$$\max_{\mathcal{E}, \alpha} \mathbb{E}_h[u(\alpha, p)]$$

for prior $h \in \Delta(\mathcal{P})$ over state of the world p

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Payoff from experiment \mathcal{E} :

$$\mathbb{E}_{e,y \sim \mathcal{E}} \max_{a \in \{0,1\}} \mathbb{E}_h[u(p, a) | e, y]$$

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- ▶ With a prior, even with two meetings, you might give the same speech at both

Ambiguity Averse Experimentation

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$$\max_{\mathcal{E}, \alpha} \lambda \mathbb{E}_{h_0}[u(\alpha, p)] + (1 - \lambda) \min_{h \in H} \mathbb{E}_h[u(\alpha, p)]$$

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Assumption 1 (Limited Extrapolation).

*For all realized experiments e , there exists an adversarial prior \mathbf{h} such that optimal decisions conditional on data are bounded away from first best
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Can be dispensed with if DM exhibits regret aversion

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then optimal experiment deterministic and Bayesian optimal for h_0

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(i) *Optimal experiment (e.g., std RCT) guarantees*

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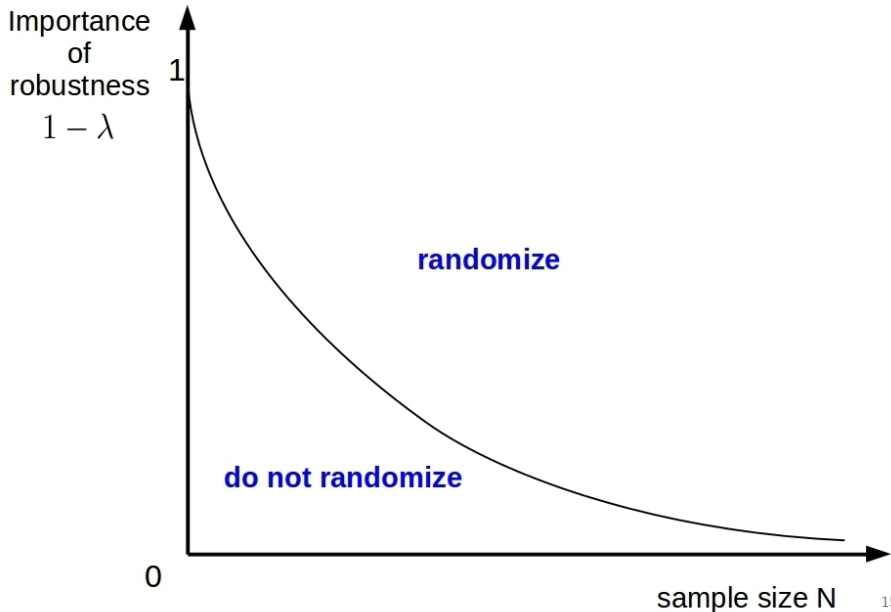
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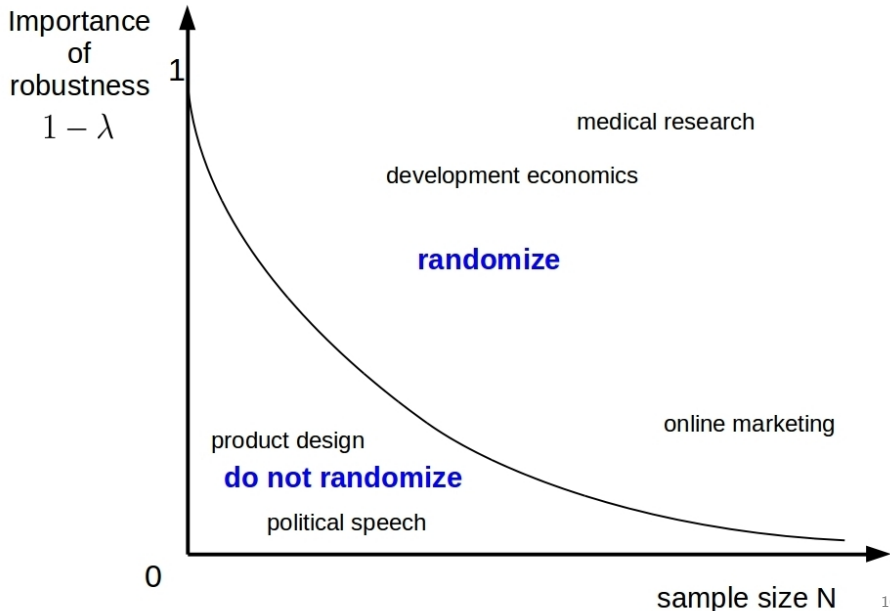
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As sample size N gets large, **optimal experiment is random**

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 - Miguel and Kremer, 2004; see Deaton, 2010 for a critique
- ▶ Implication: RCTs offer near optimal alternative to complexity of solving decision maker's problem exactly, which requires reliably eliciting beliefs (priors)

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 - In the U.S., Gender \times Race \times Age (x groups) \times Education (y groups) = $10xy$ bins
- ▶ However, these algorithms create predictable assignments
 - Is this a weakness?
 - Surprisingly, yes: “You picked the wrong variables to block on”

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- ▶ Is this a problem for robustness? Can we quantify it?

Re-Randomization

Model can be written as

$$\max_{\mathcal{E}, \alpha} \lambda \underbrace{\mathbb{E}_{\mathcal{E}}[B(e, \alpha)]}_{\text{subjective balance}} + (1 - \lambda) \underbrace{R(\mathcal{E}, \alpha)}_{\text{robustness}}$$

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1. Fixed sample of x s drawn according to pop. dist. $q \in \Delta(X)$, independently draw K assignments $\{e_1, \dots, e_K\}$ (prob. treatment = .5)

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3. Run experiment e_K^*
4. Choose policy according to $\alpha^* = \arg \max_{a \in \{0,1\}} \bar{y}^a - \bar{y}^{1-a}$

The Tradeoff of Re-Randomization

Improves balance

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Proposition 4 (negative impact on robustness).

There exists $\rho > 0$ such that, for all N , if $K \geq 2^N$, then

$$\max_{\alpha} \min_{h \in H} \mathbb{E}_{h, \mathcal{E}_K} [u(p, \alpha(e, y))] < \min_{h \in H} \mathbb{E}_h \left(\max_{a \in \{0,1\}} u(p, a) \right) - \rho.$$

How Large Are the Costs?

Proposition 5 (cost of rerandomization small).

A K -rerandomized experiment \mathcal{E}_K guarantees

$$\min_{h \in H} \mathbb{E}_{h, \mathcal{E}_K} [u(p, \alpha(e, y))] \geq \min_{h \in H} \mathbb{E}_h \left(\max_{a \in \{0,1\}} u(p, a) \right) - \sqrt{\frac{\ln(K)}{N/2}}$$

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Remark 1.

Bound remains valid regardless of objective function $B(e)$, can even choose objective ex post

Numerical Assessment

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	K	10	50	100	250	500	1000
$\sqrt{\log(K)}$		1.52	1.97	2.15	2.35	2.49	2.63
odds top 5% bal.		0.4	0.92	0.99	1.0	1.0	1.0
odds top 1% bal.		0.1	0.39	0.63	0.92	0.99	1.0

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- ▶ Morgan and Rubin (2012) show that re-randomization increases precision of estimated treatment effect in linear Gaussian model
- ▶ Bungi, Canay, and Shaikh (2016) show this more generally for balanced assignment rules (i.e., symmetric stratification)

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- ▶ Can be addressed in our framework: set $B(e) \equiv \mathbf{1}_{\text{balance} > \underline{b}}$
- ▶ If probability that a random assignment is balanced is very small, then procedure above is akin to setting K very high

Takeaway

- ▶ Ambiguity-averse experimentation as a plausible model for a range of behavior

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Takeaway

- ▶ Ambiguity-averse experimentation as a plausible model for a range of behavior
With small samples, we need to be Bayesian — learning necessarily subjective
- ▶ Re-randomization does involve a tradeoff, but cost is small
- ▶ Other questions: subgroup analysis, pre-analysis plans, . . .